

Differential Geometry II—MTG 6257—Spring 2013
Problem Set 1

1. Let (M, g) be the sphere (S^n, g_{std}) , where g_{std} (henceforth simply g) is the Riemannian metric inherited by restriction from the standard Riemannian metric g_{Euc} on \mathbf{R}^{n+1} .

(a) Let $x \in S^n$. Under the canonical identification of $T_x \mathbf{R}^{n+1}$ with \mathbf{R}^{n+1} , with what subspace of \mathbf{R}^{n+1} is $T_x S^n$ identified (in terms of x)?

(b) Recall that the canonical identification of each tangent space of \mathbf{R}^{n+1} with \mathbf{R}^{n+1} gives us an identification of {vector fields on \mathbf{R}^{n+1} } with { \mathbf{R}^{n+1} -valued functions on \mathbf{R}^{n+1} }. This identification gives meaning to the notion of “constant vector field” on \mathbf{R}^{n+1} , namely a vector field that corresponds to a constant \mathbf{R}^{n+1} -valued function. For each $v \in \mathbf{R}^{n+1}$, let $\tilde{Y}^{(v)}$ be the corresponding “constant” vector field on \mathbf{R}^{n+1} , and let $Y^{(v)}$ be the (tangent) vector field on S^n defined by $Y^{(v)}(x) := Y_x^{(v)} := \pi_x(\tilde{Y}_x^{(v)})$, where $\pi_x : T_x \mathbf{R}^{n+1} \rightarrow T_x S^n$ is orthogonal projection.

For each $v \in \mathbf{R}^{n+1}$, also define a function $f_v : S^n \rightarrow \mathbf{R}$ by $f_v(x) = v \cdot x$ (ordinary dot-product).

Recall that for any real-valued function f on a Riemannian manifold (N, h) , the *gradient* of f , denoted $\text{grad } f$, is the vector field on N defined at each $p \in N$ to be the unique vector satisfying

$$h_p((\text{grad } f)|_p, u) = \langle df|_p, u \rangle \quad \forall u \in T_p N.$$

For the Riemannian manifold (S^n, g) , show that, for each $v \in \mathbf{R}^{n+1}$,

$$\text{grad } f_v = Y^{(v)}$$

(c) Let ∇ be the Levi-Civita connection on (S^n, g) . Let $v, w \in \mathbf{R}^{n+1}$, and let $V = Y^{(v)}$, $W = Y^{(w)}$. Compute $\nabla_V W$ explicitly as an algebraic expression in terms of V, W, f_v , and f_w . (Not all of these four objects may enter your formula. “Algebraic expression” here means something whose value at each $x \in S^n$ is given explicitly by the values $V_x, W_x, f_v(x)$, and/or $f_w(x)$.)

(d) Using part (c) and the fact that ∇ is torsion-free, express the Lie bracket $[V, W]$ explicitly as an algebraic expression in terms of V, W, f_v , and f_w (where V, W are as in (c)).

(e) Let $z \in \mathbf{R}^{n+1}$, let $Z = Y^{(z)}$, let V, W be as above, and let K be the curvature of ∇ . Using the calculations above, show that

$$K(V, W)(Z) = g(W, Z)V - g(V, Z)W.$$

2. Let ∇ be a connection on a vector bundle E over a manifold M . The connection ∇ is called *flat* if its curvature K is identically zero (i.e. if $K(X, Y)(s) = 0 \in \Gamma(E)$ for all vector fields X, Y on M and all sections s of E).

Let M be an arbitrary manifold and let E be the product bundle $M \times \mathbf{R}^k$ over M . In class we defined a connection ∇ on E by identifying sections s of E with \mathbf{R}^k -valued functions f_s , and setting $(\nabla_X s)_p = X_p(f_s)$. Show that this connection is flat.

3. Let E be a vector bundle over a manifold M , and let $s \in \Gamma(E)$. Show that s is an embedding of the manifold M into the manifold E .

4. Let E be a vector bundle of rank k over a manifold M , and let ∇ be a connection on E . Let $\text{Mat}_{k \times k}(\mathbf{R})$ denote the space of all $k \times k$ matrices with real entries, and recall that $GL(k, \mathbf{R})$ is the set of all invertible such matrices, an open subset of $\text{Mat}_{k \times k}(\mathbf{R})$.

Let $U \subset M$ be open, and assume that $E|_U$ has a basis of sections $\{s_1, \dots, s_k\}$. Let $\{s'_1, \dots, s'_k\}$ be another basis of sections of $E|_U$. Necessarily, the second basis is related to the first basis by

$$s'_\mu = \sum_{\nu=1}^k s_\nu G^\nu_\mu, \quad 1 \leq \mu \leq k,$$

for a unique, smooth function $G : U \rightarrow GL(k, \mathbf{R}) \subset \text{Mat}_{k \times k}(\mathbf{R})$. (At each $p \in U$, the $G^\nu_\mu(p)$ are the entries of $G(p)$.)

Let Θ, Θ' be the connection forms of ∇ relative to the bases $\{s_1, \dots, s_k\}$ and $\{s'_1, \dots, s'_k\}$, respectively. Show that

$$\Theta' = G^{-1}\Theta G + G^{-1}dG, \tag{1}$$

where G^{-1} and G are treated as matrices whose entries are real-valued functions; Θ, Θ' , and dG are treated as matrices whose entries are real-valued 1-forms; and $(dG)^\mu_\nu = d(G^\mu_\nu)$. Helpful observation: (1) is equivalent to

$$\Theta'(X) = G^{-1}\Theta(X)G + G^{-1}X(G) \quad \forall X \in \Gamma(TM|_U). \tag{2}$$

In (2), all of the objects $\Theta'(X), \Theta(X), G^{-1}, G$, and $X(G)$ may be viewed either as $\text{Mat}_{k \times k}$ -valued functions, or as matrices whose entries are real-valued functions. In the former point of view, at each $p \in U$, $X_p(G)$ is the directional derivative of the $\text{Mat}_{k \times k}$ -valued function G in the direction $X_p \in T_p M$; in the latter point of view, $X_p(G)$ is a matrix whose $(\mu, \nu)^{\text{th}}$ entry is $X_p(G^\mu_\nu)$.