

Differential Geometry—MTG 6257—Spring 2026

Problem Set 4

Due-date: Wednesday, 4/22/26

**Required reading:** All the problems, and the handout “Pullbacks of vector bundles and connections”.

**Required problems (to be handed in):** 1, 2, 3bc, 4, 5ac.

In doing any of these problem parts, you may assume the results of all earlier problems and problem-parts (optional or required).

**Optional problems:** All the ones that are not required.

Notation for all the problems: unless otherwise specified,  $M$  is an  $n$ -dimensional manifold. (Some problems may still state this explicitly.)

1. Let  $(M, g) = (\mathbf{R}^3, g_{\text{std}})$  and let  $(x, y, z)$  denote the standard coordinates. Let  $U \subset \mathbf{R}^2$  be an open neighborhood of  $(0, 0)$ , let  $f : U \rightarrow \mathbf{R}$ , and let  $Q \subset \mathbf{R}^3$  be the graph of  $f$ . Assume that  $f(0, 0) = 0$  and that  $df|_{(0,0)} = 0$ , so that the plane in  $\mathbf{R}^3$  tangent to  $Q$  at  $(0, 0, 0)$  (the “embedded tangent space” at the origin) is the  $xy$  plane. Let  $N$  be the upward-pointing normal vector field (i.e. the one whose  $z$ -component is positive). Let  $\bar{h}$  be the scalar second fundamental form of  $Q$  determined by  $N$ .

The Taylor expansion of  $f$  near  $(0, 0)$  is of the form  $f(x, y) = \frac{1}{2}(ax^2 + 2bxy + cy^2) +$  (higher-order remainder). Express  $\bar{h}$  at the origin in terms of  $a, b$ , and  $c$ .

Figure out how this generalizes to graphs of functions  $f : (U \subset \mathbf{R}^n) \rightarrow \mathbf{R}$ .

**Remark.** For any hypersurface ( $:=$  codimension-one submanifold)  $Q \subset \mathbf{R}^n$ , and any  $p \in Q$ , we can rotate and translate the coordinate axes in  $\mathbf{R}^n$  to make  $p$  the origin and  $T_p Q$  the hyperplane  $H = \{(x^1, \dots, x^n) \in \mathbf{R}^n \mid x^n = 0\}$ . The Implicit Function Theorem then implies that, near the origin,  $Q$  is the graph of a function  $f : (U \subset H) \rightarrow \mathbf{R}$ . So, your work above provides a general interpretation of the second fundamental form of a hypersurface in  $\mathbf{R}^n$ : it describes the second-order deviation of the surface from its tangent plane at any point. (There is no first-order deviation; that’s what “tangent plane” means.) This is one reason the second fundamental form of a submanifold of  $\mathbf{R}^n$  is often called the “extrinsic curvature” of the submanifold; it’s something that an observer in  $\mathbf{R}^n$ , *external* to the submanifold, might describe as “curvature.” The Riemann tensor of a submanifold of  $\mathbf{R}^n$  is thought of as “intrinsic curvature”: once one has the metric on  $Q$ , nothing involving the ambient manifold is needed to define or compute the Riemann tensor.

**2. Lemma for use in next problem.** Let  $\{y^i\}$  be standard coordinates on  $\mathbf{R}^n$ , let  $\omega \in \Omega^{n-1}(S^{n-1})$  be the standard volume form and let  $\text{Vol}(S^{n-1}) = \int_{S^{n-1}} \omega$  (the volume of the standard, Euclidean, unit sphere).<sup>1</sup> Show that for all  $i, j \in \{1, \dots, n\}$ ,

$$\int_{S^{n-1}} y^i y^j \omega = \frac{1}{n} \delta_{ij} \text{Vol}(S^{n-1}).$$

(This can be done without any trigonometric integrals.)

*Note:*  $\text{Vol}(S^{n-1})$  can be computed explicitly. I simply am not asking you to do the computation. (However, it can be reduced to a trigonometric integral of the type we teach “reduction formulas” for in Calc 1.)

**3. Ricci tensor and scalar curvature.** Let  $(M, g)$  be a Riemannian manifold. For each  $p \in M$  and  $X, Y \in T_p M$ , the Riemann tensor determines a linear map  $T_p M \rightarrow T_p M$  defined by  $Z \mapsto R(X, Z)Y$ . Define

$$\text{Ric}(X, Y) = \text{Ric}|_p(X, Y) = \text{tr}(Z \mapsto R(X, Z)Y),$$

where “tr” denotes the trace. Thus, if  $\{e_i\}$  is an arbitrary basis of  $T_p M$  and  $\{\theta^i\}$  is the dual basis of  $T_p^* M$ ,

$$\text{Ric}(X, Y) = \langle \theta^i, R(X, e_i)Y \rangle.$$

Clearly the map  $(X, Y) \mapsto \text{Ric}|_p(X, Y)$  is bilinear, so  $\text{Ric}|_p$  is an element of  $T_p^* M \otimes T_p^* M$ . This bilinear form is called the *Ricci tensor* at  $p$ . Letting  $p$  vary, it is easily seen that  $\text{Ric}|_p$  depends smoothly on  $p$ , so  $\text{Ric}$  becomes a tensor field on  $M$ , called the *Ricci tensor* (field) or the *Ricci curvature*.

(a) Show that with  $p, \{e_i\}, \{\theta^i\}$  as above, the Ricci tensor at  $p$  is given by

$$\begin{aligned} \text{Ric} &= R_{jl} \theta^j \otimes \theta^l, \\ &\text{where } R_{jl} = R^i{}_{jil} \end{aligned}$$

and where  $\{R^i{}_{jkl}\}$  are the components of the Riemann tensor at  $p$  with respect to the given bases.

(b) Show that the Ricci tensor is a *symmetric* tensor field: for all  $p \in M$  and all  $X, Y \in T_p M$ , we have  $\text{Ric}(X, Y) = \text{Ric}(Y, X)$ .

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<sup>1</sup>You will not need a formula for  $\omega$  to do this problem, but as a reminder, one definition is  $\omega = j^*(\iota_N(dy^1 \wedge dy^2 \wedge \dots \wedge dy^n))$ , where  $j : S^{n-1} \hookrightarrow \mathbf{R}^n$  is the inclusion map and  $N = \sum_i y^i \frac{\partial}{\partial y^i}$ , a vector field on  $\mathbf{R}^n$  that restricts to the outward-pointing unit normal vector field along  $S^{n-1}$ .

Suggestion: Compute the trace defining  $\text{Ric}(X, Y)$  using an orthonormal basis of  $T_pM$ . The dual pairing with  $\theta^i$  then becomes inner product with  $e_i$ .

(c) Below, for any normed vector space  $V$ , we write  $S(V)$  for the unit sphere centered at the origin.

Assume that  $n = \dim(M) \geq 2$ . Recall that, at each  $p$ , the sectional curvature of  $M$  at  $p$  is a map  $G_2(T_pM) \rightarrow \mathbf{R}$ ,  $\mathcal{P} \mapsto \sigma(\mathcal{P})$ . For  $X \in S(T_pM)$  let  $X^\perp = \{Y \in T_pM : Y \perp X\}$ . Let  $G_2^X(T_pM) \subset G_2(T_pM)$  denote the set of all 2-planes in  $T_pM$  that contain  $X$ . There is a two-to-one map

$$\begin{aligned} \pi_X : S(X^\perp) &\rightarrow G_2^X(T_pM), \\ \pi_X(Y) &= \mathcal{P}(X, Y) := \text{span}\{X, Y\}. \end{aligned}$$

(The “two-to-one” comes from the fact that  $\pi_X(-Y) = \pi_X(Y)$ .) The vector space  $X^\perp$  is a Riemannian manifold with the standard Riemannian metric determined by  $g_p|_{X^\perp}$ ; thus  $S(X^\perp)$  inherits a Riemannian metric. Orienting  $X^\perp$  arbitrarily, and giving  $S^{n-1}$  the induced orientation, we then obtain a volume form  $\omega_{n-2}$  on  $S(X^\perp)$ . (The subscript here is just a reminder of the dimension of  $S(X^\perp)$ .) Show that for  $X \in S(T_pM)$ ,

$$\int_{S(X^\perp)} (\sigma \circ \pi_X) \omega_{n-2} = \int_{S(X^\perp)} \sigma(\mathcal{P}(X, \cdot)) \omega_{n-2} = \frac{\text{Vol}(S^{n-2})}{n-1} \text{Ric}(X, X), \quad (1)$$

and hence

$$\frac{1}{n-1} \text{Ric}(X, X) = \frac{1}{\text{Vol}(S(X^\perp))} \int_{S(X^\perp)} (\sigma \circ \pi_X) \omega_{n-2}. \quad (2)$$

(Thus, up to the normalization constant  $\frac{1}{n-1}$ , for each unit vector  $X \in T_pM$  the quantity  $\text{Ric}(X, X)$  represents the *average sectional curvature among all two-planes in  $T_pM$  that contain  $X$* .)<sup>2</sup>

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<sup>2</sup>The reason we integrated over  $S(X^\perp)$  in (1) and (2), rather than over  $G_2^X(T_pM)$ , is that  $G_2^X(T_pM)$  is diffeomorphic to the projective space  $\mathbf{RP}^{n-2}$ , which is not orientable when  $n$  is even. However, whether or not a Riemannian manifold  $(N, g_N)$  is orientable, the metric  $g_N$  induces a well-defined measure “ $d\mu_N$ ” on  $N$ ; it’s simply something that we did not discuss in the non-orientable case (it’s not a differential form in that case). Therefore for any finite-dimensional inner-product space  $W$ , the projectization  $\mathbf{P}(W)$  has a Riemannian metric, hence Riemannian measure  $d\mu$ , induced the by the natural two-to-one covering map  $\pi' : S(W) \rightarrow \mathbf{P}(W)$  and the standard Riemannian metric on  $S(W)$ . (Here we regard  $W$  as a Riemannian manifold with the standard Riemannian metric determined by the given inner product on  $W$ .) Using these facts it can be shown  $\text{Vol}(S(X^\perp)) = 2\text{Vol}(G_2^X(T_pM))$  and that [\[FOOTNOTE CONTINUES ON NEXT PAGE\]](#)

**Remark 1 (covered in class)** Recall that for any finite-dimensional vector space  $V$ , any symmetric bilinear form  $h : V \times V \rightarrow \mathbf{R}$  is determined by its restriction to the diagonal: if we know  $h(X, X)$  for all  $X \in V$ , then we know  $h(X, Y)$  for all  $X, Y \in V$ . This follows from the *polarization identity*

$$h(X, Y) = \frac{h(X + Y, X + Y) - h(X - Y, X - Y)}{4}.$$

Furthermore, if  $V$  is equipped with a norm  $\| \cdot \|$ , then for all nonzero  $X \in V$  we have  $h(X, X) = \|X\|^2 h(\hat{X}, \hat{X})$ , where  $\hat{X} = X/\|X\|$ . Thus, in the presence of a norm, a symmetric bilinear form  $h$  can be completely recovered from the function  $f_h$  (notation just for this problem) that  $h$  determines on the unit sphere:

$$\begin{aligned} f_h : S(V) := \{X \in V : \|X\| = 1\} &\rightarrow \mathbf{R}, \\ X &\mapsto f_h(X) := h(X, X). \end{aligned}$$

In particular, for each  $p \in M$ , the function  $f_{\text{Ric}} : S(T_p M) \subset T_p M$  carries all the information of the Ricci tensor at  $p$ .

(d) Let  $\mathfrak{g}_p : T_p M \rightarrow T_p^* M$  be the isomorphism induced by the inner product  $g_p$ . For any tensor  $h_p \in T_p^* M \otimes T_p^* M$ , we define the *trace of  $h_p$  with respect to  $g_p$* , denoted  $\text{tr}_{g_p}(h_p)$ , to be the image of  $h_p$  under the following composition

$$T_p^* M \otimes T_p^* M \xrightarrow{\mathfrak{g}_p^{-1} \otimes \text{id}} T_p M \otimes T_p M \xrightarrow{\text{canon. iso.}} \text{Hom}(T_p M, T_p M) \xrightarrow{\text{trace}} \mathbf{R}.$$

Applying this pointwise to any  $h \in \Gamma(\text{Sym}^2(T^* M))$  gives a real-valued function  $\text{tr}_g(h) : M \rightarrow \mathbf{R}$ .

Show that for  $h$  as above,  $p \in M$ ,  $\{e_i\}$  any basis of  $T_p M$ ,

$$\text{tr}_g(h)|_p = g^{ij} h_{ij} = h^i{}_i = h_i{}^i,$$

where  $h_{ij} = h(e_i, e_j)$ ,  $g \cdot \cdot$  is the matrix of  $g_p$  with respect to the basis  $\{e_i\}$  (i.e.  $g_{ij} = g(e_i, e_j)$ ), and  $g \cdot \cdot = (g \cdot \cdot)^{-1}$ .

(e) The *scalar curvature* or *Ricci scalar* is the real-valued function  $R = \text{tr}_g(\text{Ric})$  on  $M$ . Show that at each  $p \in M$ ,

$$\int_{S(X^\perp)} (\sigma \circ \pi_X) \omega = 2 \int_{G_2^X(T_p M)} \sigma \, d\mu.$$

Thus (2) indeed represents the average value of the function  $\sigma|_{G_2^X(T_p M)}$  with respect to the induced measure on  $G_2^X(T_p M)$ .

$$\frac{1}{n}R(p) = \frac{1}{\text{Vol}(S^{n-1})} \int_{S(T_p M)} f_{\text{Ric}} \omega_{n-1},$$

where  $f_{\text{Ric}}$  is as in Remark 1 and  $\omega_{n-1}$  is the volume form on the sphere  $S(T_p M)$  induced by the metric  $g_p$  and an arbitrary choice of orientation of  $T_p M$ .

Thus, up to the normalization constant  $\frac{1}{n}$ , the scalar curvature at  $p$  is the average value of the function  $S(T_p M) \rightarrow \mathbf{R}, X \mapsto \text{Ric}(X, X)$ . But for each  $X \in S(T_p M)$ , the quantity  $f_{\text{Ric}}(X)$  is itself an average of sectional curvatures (up to a factor of  $\frac{1}{n-1}$ ), so scalar curvature is sometimes thought of as a “double average” of sectional curvatures. However, the word “double” can be eliminated: it can be shown that, up to a dimensional constant,  $R(p)$  is simply the average value of the sectional-curvature function  $\sigma_p : G_2(T_p M) \rightarrow \mathbf{R}$ .

4. For  $(M, g) = (S^n, g_{\text{std}})$ , compute the Ricci tensor and scalar curvature. (You should find that the Ricci tensor is a constant multiple of  $g_{\text{std}}$  and that the scalar curvature is constant.)

## 5. Connections on the pulled-back tangent bundle

Before doing this problem you should read the notes “Pullbacks of Vector Bundles and Connections”. The notation “ $F^\sharp$ ” (with “ $F$ ” called “ $f$ ”) is defined in Section 2 of these notes.

Let  $F : N \rightarrow M$  be a smooth map of manifolds. As discussed last semester, a vector field on  $N$  does not, in general, push forward to a vector field on  $M$ . However, it *does* push forward to a section of the pulled-back tangent bundle: Given  $X \in \Gamma(TN)$ , we can define a section  $\hat{X} \in \Gamma(F^*TM)$  by

$$\hat{X}_p := F_p^\sharp(F_{*p}X_p). \quad (3)$$

(a) Let  $\nabla'$  be an arbitrary connection on  $F^*(TM)$  (not necessarily pulled back from a connection on  $TM$ ). Consider the bilinear, antisymmetric “pseudo-torsion” map  $\tilde{\tau}_\psi = \tilde{\tau}_\psi^{\nabla'} : \Gamma(TN) \times \Gamma(TN) \rightarrow \Gamma(F^*(TM))$  defined by

$$\tilde{\tau}_\psi(X, Y) = \nabla'_X \hat{Y} - \nabla'_Y \hat{X} - \widehat{[X, Y]}.$$

(The subscript  $\psi$  is for “pseudo”; there is no object “ $\psi$ ” here.)

Show that  $\tilde{\tau}_\psi$  is  $\mathcal{F}(N)$ -bilinear, hence tensorial, defining a section  $\tau_\psi = \tau_\psi^{\nabla'} \in \Omega^2(N; F^*(TM))$ .

(b) We may view (3) as the definition of a canonical  $F^*(TM)$ -valued 1-form  $I_\psi$  on  $N$ ,

$$I_\psi(X_p) = \hat{X}_p = F_p^\sharp(F_{*p}X_p).$$

Show that  $\tau_\psi = d_{\nabla'} I_\psi$ .

(c) Show that the condition  $\tau_\psi^{\nabla'} \equiv 0$  is equivalent to the statement that for all local-coordinate systems  $\{x^i\}$  on  $N$ ,

$$\nabla'_{\frac{\partial}{\partial x^i}} \left( \widehat{\frac{\partial}{\partial x^j}} \right) = \nabla'_{\frac{\partial}{\partial x^j}} \left( \widehat{\frac{\partial}{\partial x^i}} \right) \quad \text{for all } i, j. \quad (4)$$

(d) Show that if  $\nabla'$  is the pullback of a connection  $\nabla$  on  $TM$  whose torsion is  $\tau = \tau^\nabla$ , then  $\tau_\psi^{\nabla'} = F^*\tau$ , where we define  $F^*\tau$  pointwise by

$$(F_p^*\tau)_p(X_p, Y_p) := F_p^\# (\tau_{F(p)}(F_{*p}X_p, F_{*p}Y_p)), \quad p \in N.$$

*Hint:* Fix an arbitrary point  $p \in N$  and let  $\{x^i\}, \{y^i\}$  be local coordinates on a neighborhood of  $p, F(p)$  respectively. Compute  $\tilde{\tau}_\psi \left( \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j} \right)$ . The Jacobian  $\left( \frac{\partial y^i}{\partial x^j} \right)$  will enter your calculation.

(e) Use earlier parts of this problem to show that if  $\nabla$  is any torsion-free connection on  $TM$  (e.g. the Levi-Civita connection of a Riemannian metric), then (4) holds.

**Remark 2** This underlies and generalizes a crucial step in the derivation of formulas for the first and second variations of the arclength and energy functions on the space of paths between two points in  $M$ .